



Future Grid Introduction

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www.futuregrid.org

MAGIC Meeting

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FutureGrid Goals

- **Support the research** on the future of distributed, grid, and cloud computing.
- Build a robustly managed simulation environment or testbed to support the development and early use in science of new technologies at all levels of the software stack: from **networking to middleware to scientific applications**.
- Mimic TeraGrid and/or general parallel and distributed systems – **FutureGrid is part of TeraGrid** and one of two **experimental** TeraGrid systems (the other is based on **GPU**)
- Enable major advances in science and engineering through collaborative development of science applications and related software using FG
- FutureGrid is a (small 5600 core) **Science Cloud** but it is more accurately a **virtual machine based simulation environment**



FutureGrid Hardware



System type	# CPUs	# Cores	TFLOPS	RAM (GB)	Secondary storage (TB)	Default local file system	Site
Dynamically configurable systems							
IBM iDataPlex	256	1024	11	3072	335*	Lustre	IU
Dell PowerEdge	192	1152	12	1152	15	NFS	TACC
IBM iDataPlex	168	672	7	2016	120	GPFS	UC
IBM iDataPlex	168	672	7	2688	72	Lustre/PVFS	UCSD
Subtotal	784	3520	37	8928	542		
Systems not dynamically configurable							
Cray XT5m	168	672	6	1344	335*	Lustre	IU
Shared memory system TBD	40**	480**	4**	640**	335*	Lustre	IU
Cell BE Cluster	4						
IBM iDataPlex	64	256	2	768	5	NFS	UF
High Throughput Cluster	192	384	4	192			PU
Subtotal	552	2080	21	3328	10		
Total	1336	5600	58	10560	552		

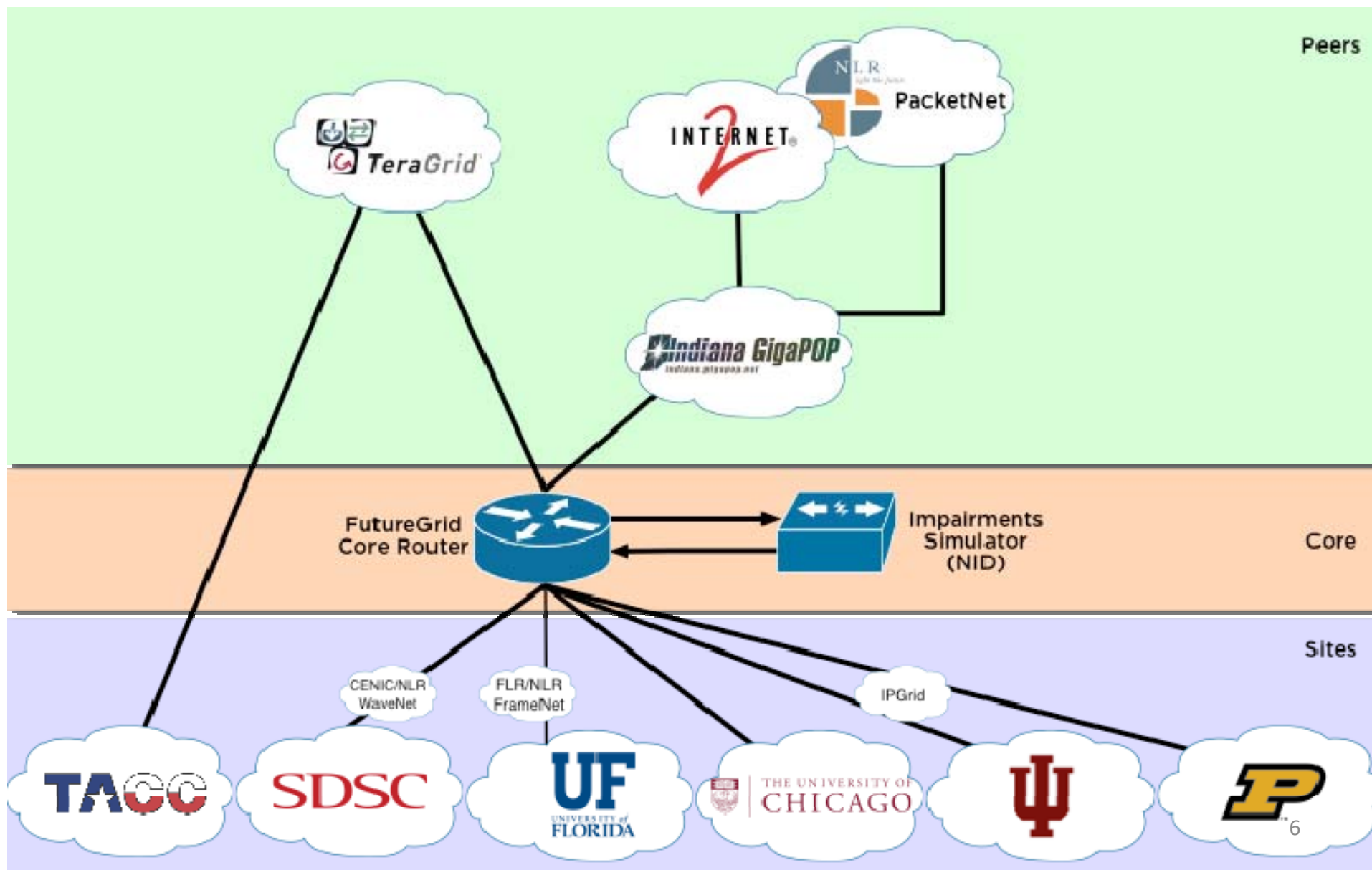
- FutureGrid has **dedicated network** (except to TACC) and a **network fault and delay generator**
- Can isolate experiments on request; IU runs Network for NLR/Internet2
- (Many) **additional partner machines** will run FutureGrid software and be supported (but allocated in specialized ways)



Storage Hardware

System Type	Capacity (TB)	File System	Site	Status
DDN 9550 (Data Capacitor)	339	Lustre	IU	Existing System
DDN 6620	120	GPFS	UC	New System
SunFire x4170	72	Lustre/PVFS	SDSC	New System
Dell MD3000	30	NFS	TACC	New System

Logical Diagram





FutureGrid Partners

- [Indiana University](#) (Architecture, core software, Support)
- [Purdue University](#) (HTC Hardware)
- [San Diego Supercomputer Center](#) at University of California San Diego (INCA, Monitoring)
- [University of Chicago](#)/Argonne National Labs (Nimbus)
- [University of Florida](#) (ViNE, Education and Outreach)
- University of Southern California Information Sciences (Pegasus to manage experiments)
- University of Tennessee Knoxville (Benchmarking)
- [University of Texas at Austin](#)/Texas Advanced Computing Center (Portal)
- University of Virginia (OGF, Advisory Board and allocation)
- Center for Information Services and GWT-TUD from Technische Universität Dresden. (VAMPIR)
- [Blue institutions](#) have FutureGrid hardware



Other Important Collaborators



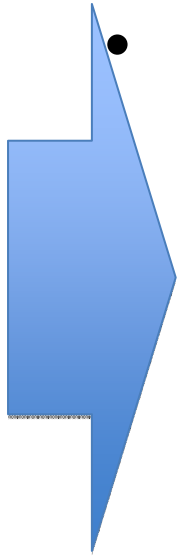
- NSF
- Early users from an application and computer science perspective and from both research and education
- Grid5000/Aladin and D-Grid in Europe
- Commercial partners such as
 - Eucalyptus
 - Microsoft (Dryad + Azure) – Note current Azure external to FutureGrid as are GPU systems
 - Application partners
- TeraGrid
- Open Grid Forum
- Open Nebula, Open Cirrus Testbed, Open Cloud Consortium, Cloud Computing Interoperability Forum. IBM-Google-NSF Cloud, UIUC Cloud



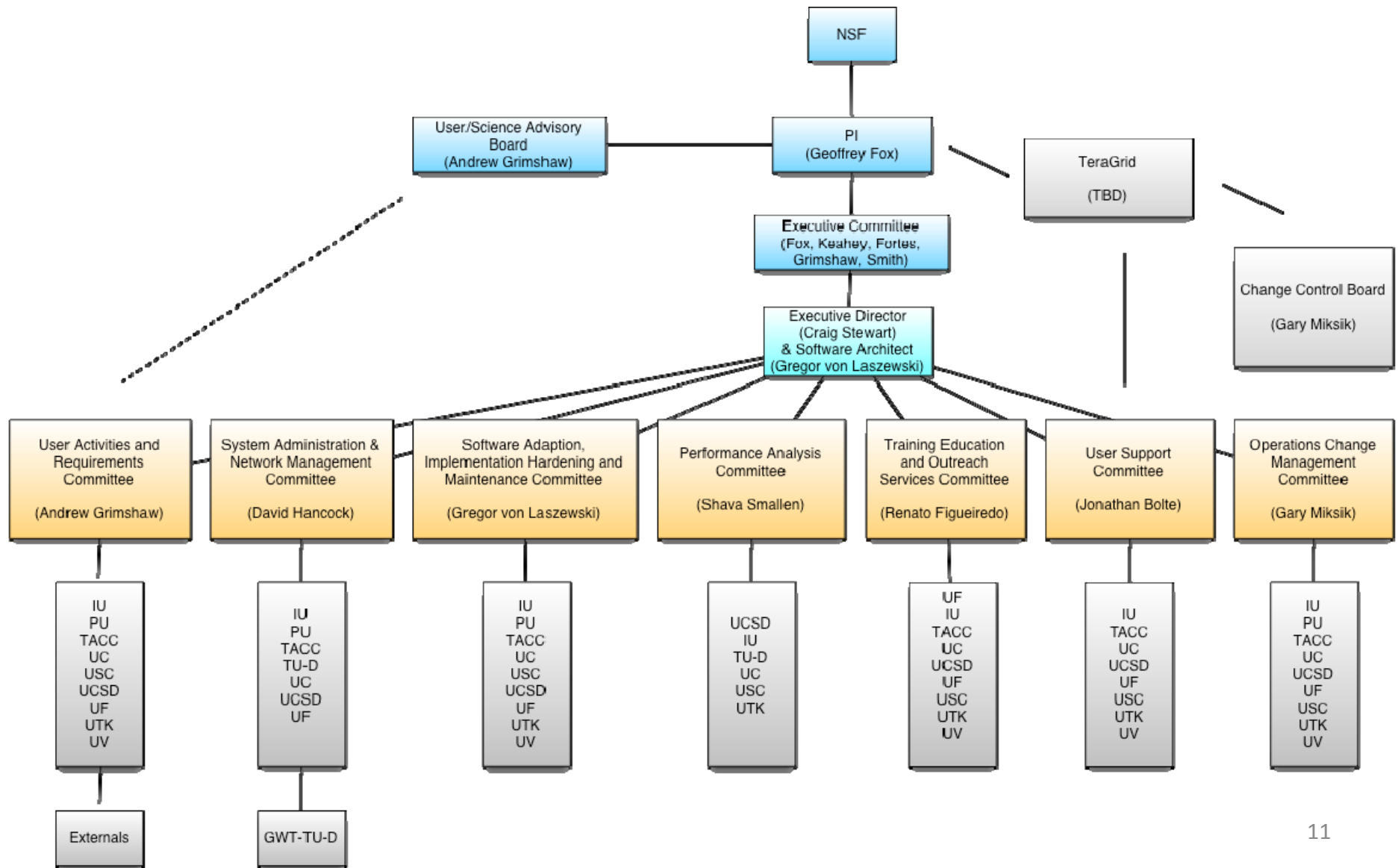
FutureGrid Usage Scenarios

- Developers of **end-user applications** who want to develop new applications in cloud or grid environments, including analogs of commercial cloud environments such as Amazon or Google.
 - Is a Science Cloud for me?
- Developers of end-user applications who want to experiment with multiple hardware environments.
- Grid/Cloud **middleware developers** who want to evaluate new versions of middleware or new systems.
- **Networking researchers** who want to test and compare different networking solutions in support of grid and cloud applications and middleware. (Some types of networking research will likely best be done via through the GENI program.)
- **Education** as well as research
- Interest in performance requires **close to OS support**

Future Grid Users

- Application/Scientific users
 - System administrators
 - Software developers
 - Testbed users
 - Performance modelers
 - Educators
 - Students
- 
- A large blue arrow pointing from the left column of users to the right column of support.
- Supported by FutureGrid Infrastructure & Software offerings

Management Structure





FutureGrid Working Groups

- **Systems Administration and Network Management Committee:** This committee will be responsible for all matters related to systems administration, network management, and security. David Hancock of IU will be the inaugural chair of this committee.
- **Software Adaptation, Implementation, Hardening, and Maintenance Committee:** This committee will be responsible for all aspects of software creation and management. It should interface with TAIS in TeraGrid. Gregor von Laszewski from IU will chair this committee.
- **Performance Analysis Committee:** This committee will be responsible for coordination of performance analysis activities. Shava Smallen of UCSD will be the inaugural chair of this committee.
- **Training, Education, and Outreach Services Committee:** This committee will coordinate Training, Education, and Outreach Service activities and will be chaired by Renato Figueiredo.
- **User Support Committee:** This committee will coordinate the management of online help information, telephone support, and advanced user support. Jonathan Bolte of IU will chair this committee.
- **Operations and Change Management Committee (including CCB):** This committee will be responsible for operational management of FutureGrid, and is the one committee that will always include at least one member from every participating institution, including those participating without funding. This is led by Craig Stewart

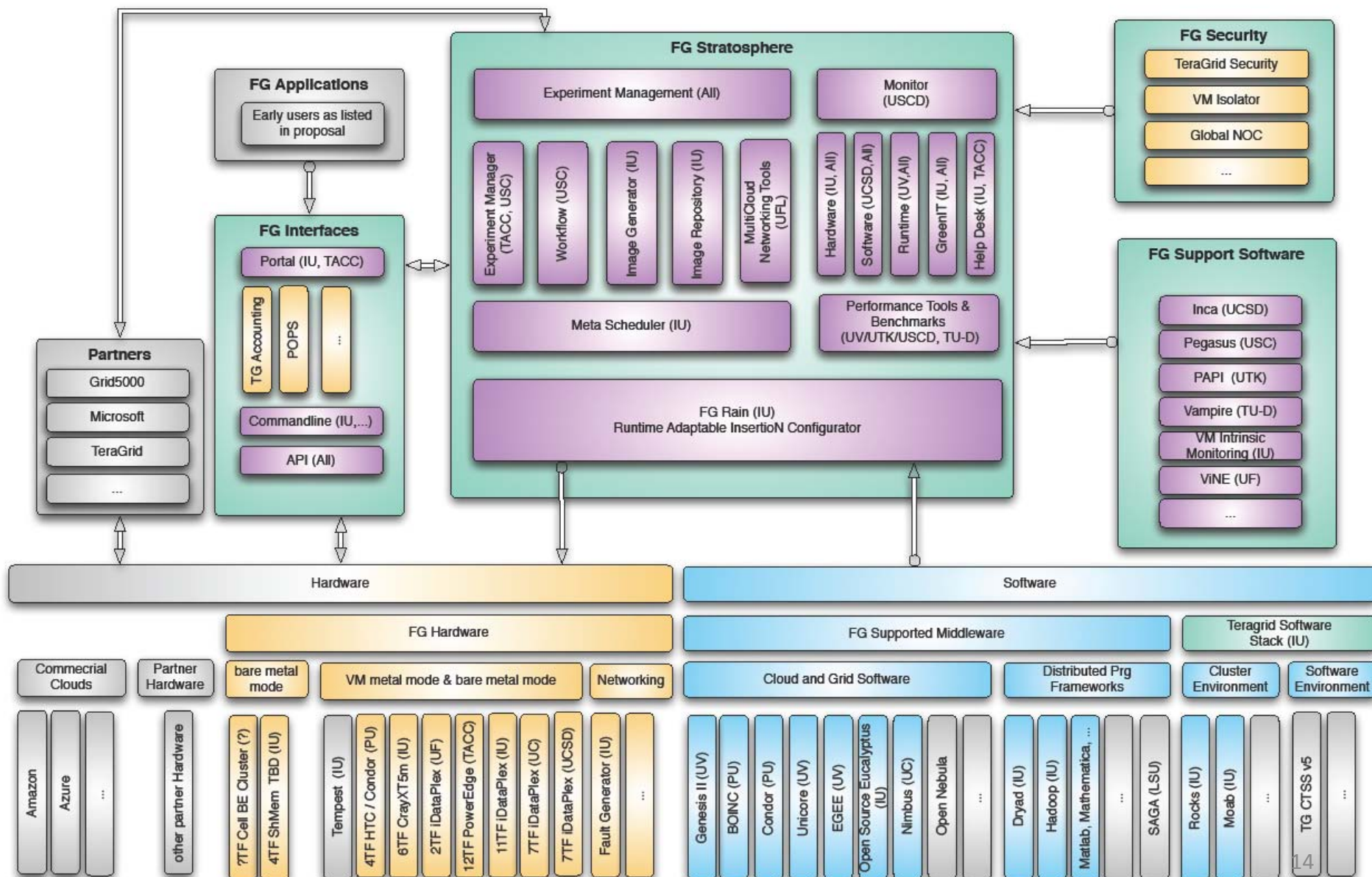


FutureGrid Architecture

- Open Architecture allows **to configure** resources based on images
- Managed images allows **to create** similar experiment environments
- Experiment management allows **reproducible activities**
- Through our modular design we allow **different clouds and images** to be “rained” upon hardware.
- Note will be **supported 24x7** at “TeraGrid Production Quality”
- Will support deployment of **“important” middleware** including TeraGrid stack, Condor, BOINC, gLite, Unicore, Genesis II



FutureGrid Architecture





Development Phases

- Phase 0: Get Hardware to run
- Phase I: Get early users to use the system
- Phase II: Implement Dynamic Provisioning
- Phase III: Integrate with TeraGgrid



Objectives: Software

- Extensions to existing software
- Existing open-source software
- Open-source, integrated suite of software to
 - instantiate and execute grid and cloud experiments.
 - perform an experiment
 - collect the results
 - tools for instantiating a test environment,
 - Torque, MOAB, xCAT, bcfg, and Pegasus, Inca, ViNE, a number of other tools from our partners and the open source community
 - Portal to interact
 - Benchmarking

FG Stratosphere

- Objective
 - Higher than a particular cloud
 - Provides all mechanisms to provision a cloud on a given FG hardware
 - Allows the management of reproducible experiments
 - Allows monitoring of the environment and the results
- Risks
 - Lots of software
 - Possible multiple path to do the same thing
- Good news
 - We know about different solutions and have identified a very good plan with risk mitigation plans



Rain



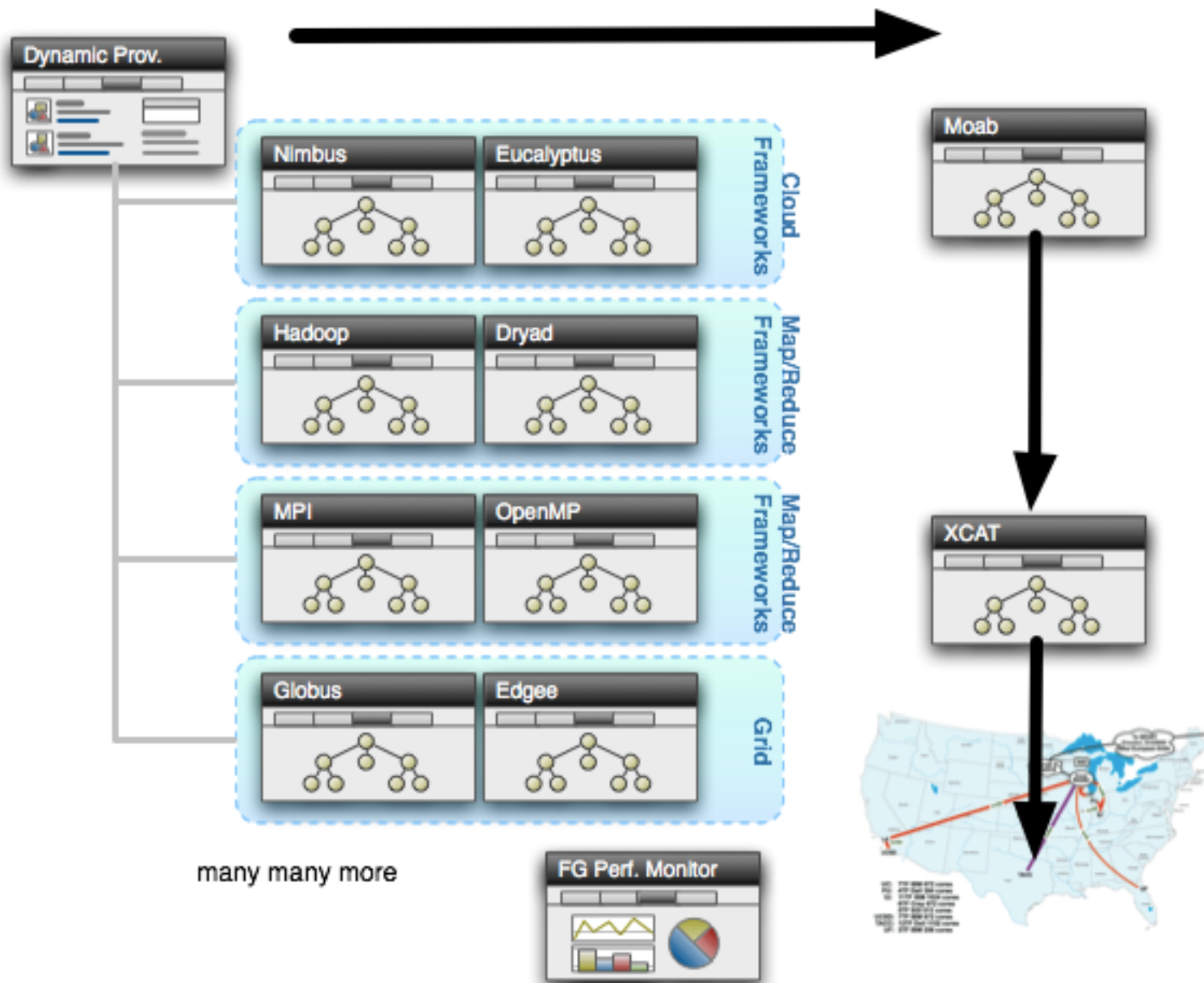
Runtime Adaptable Insertion Service

- Objective
 - Provide dynamic provisioning
 - Running outside virtualization
 - Cloud neutral
 - Nimbus, Eucalyptus, ...
 - Future oriented
 - Dryad
 - ...
- Risks
 - Some frameworks (e.g. MS) are more complex to provision

Dynamic Provisioning

- Change underlying system to support current user demands
 - Linux, Windows, Xen, Nimbus, Eucalyptus, Hadoop, Dryad
 - Switching between Linux and Windows possible!
- Stateless images
 - Shorter boot times
 - Easier to maintain
- Stateful installs
 - Windows
- Use Moab to trigger changes and xCAT to manage installs

Dynamic Provisioning





Dynamic provisioning Examples



- Give me a virtual cluster with 30 nodes
- Give me a Eucalyptus environment with 10 nodes
- Give me a hadoop environment with x nodes
- Run my application on hadoop, dryad, ... and compare the performance

Command line

- fg-deploy-image
 - host name
 - image name
 - start time
 - end time
 - label name
- fg-add
 - label name
 - framework hadoop
 - version 1.0
- Deploys an image on a host
- Adds a feature to a deployed image

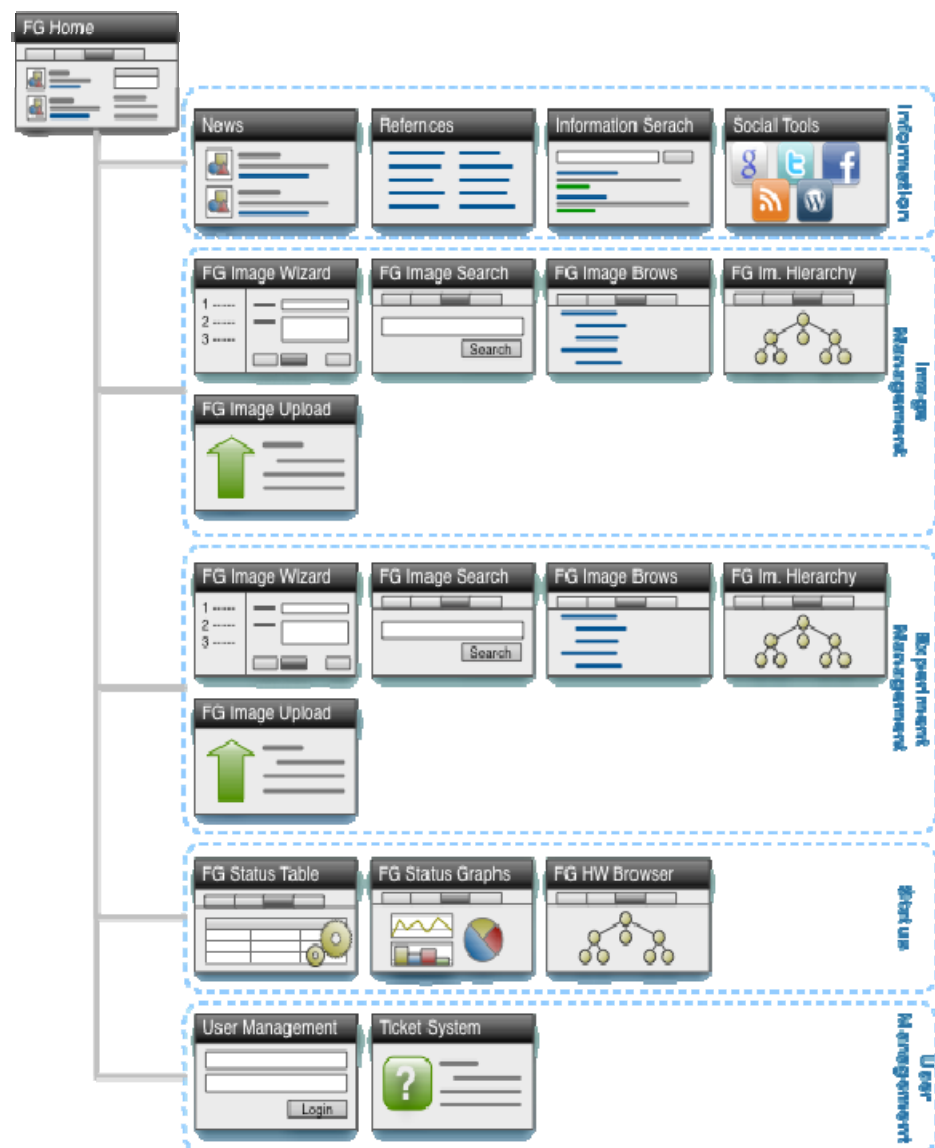
xCAT and Moab

- xCAT
 - uses installation infrastructure to perform installs
 - creates stateless Linux images
 - changes the boot configuration of the nodes
 - remote power control and console (IPMI)
- Moab
 - meta-schedules over resource managers
 - TORQUE and Windows HPC
 - control nodes through xCAT
 - changing the OS
 - remote power control

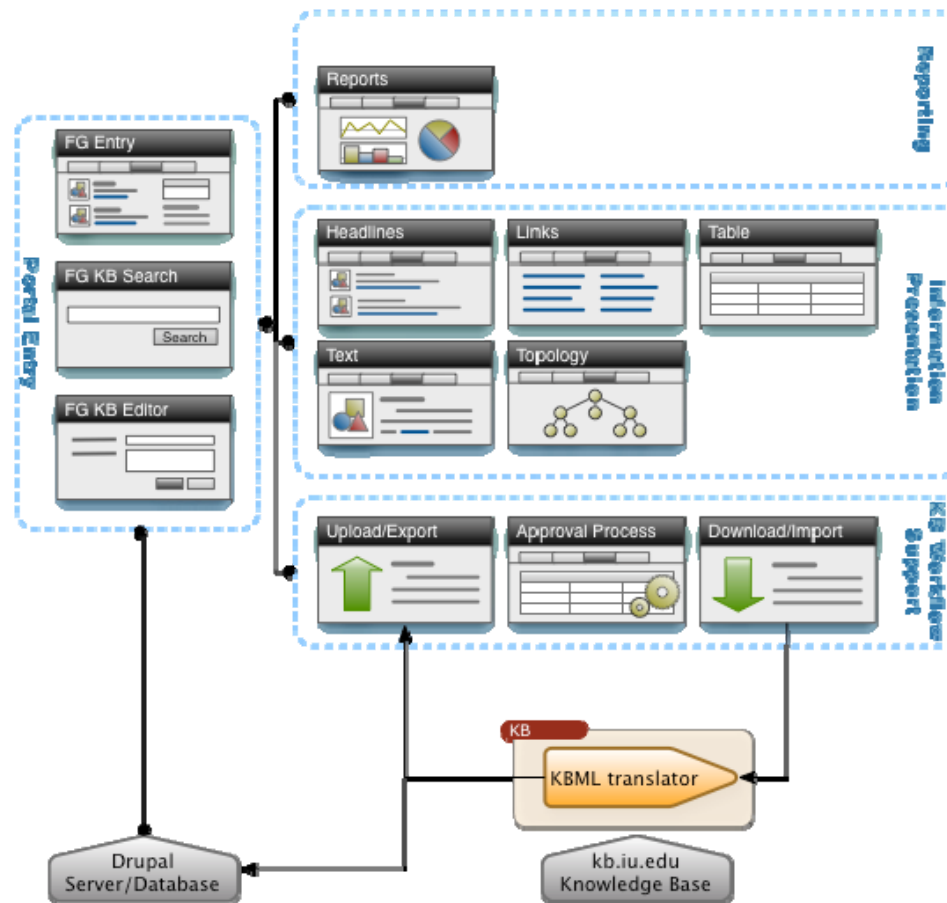
Experiment Manager

- Objective
 - Manage the provisioning for reproducible experiments
 - Coordinate workflow of experiments
 - Share workflow and experiment images
 - Minimize space through reuse
- Risk
 - Images are large
 - Users have different requirements and need different images

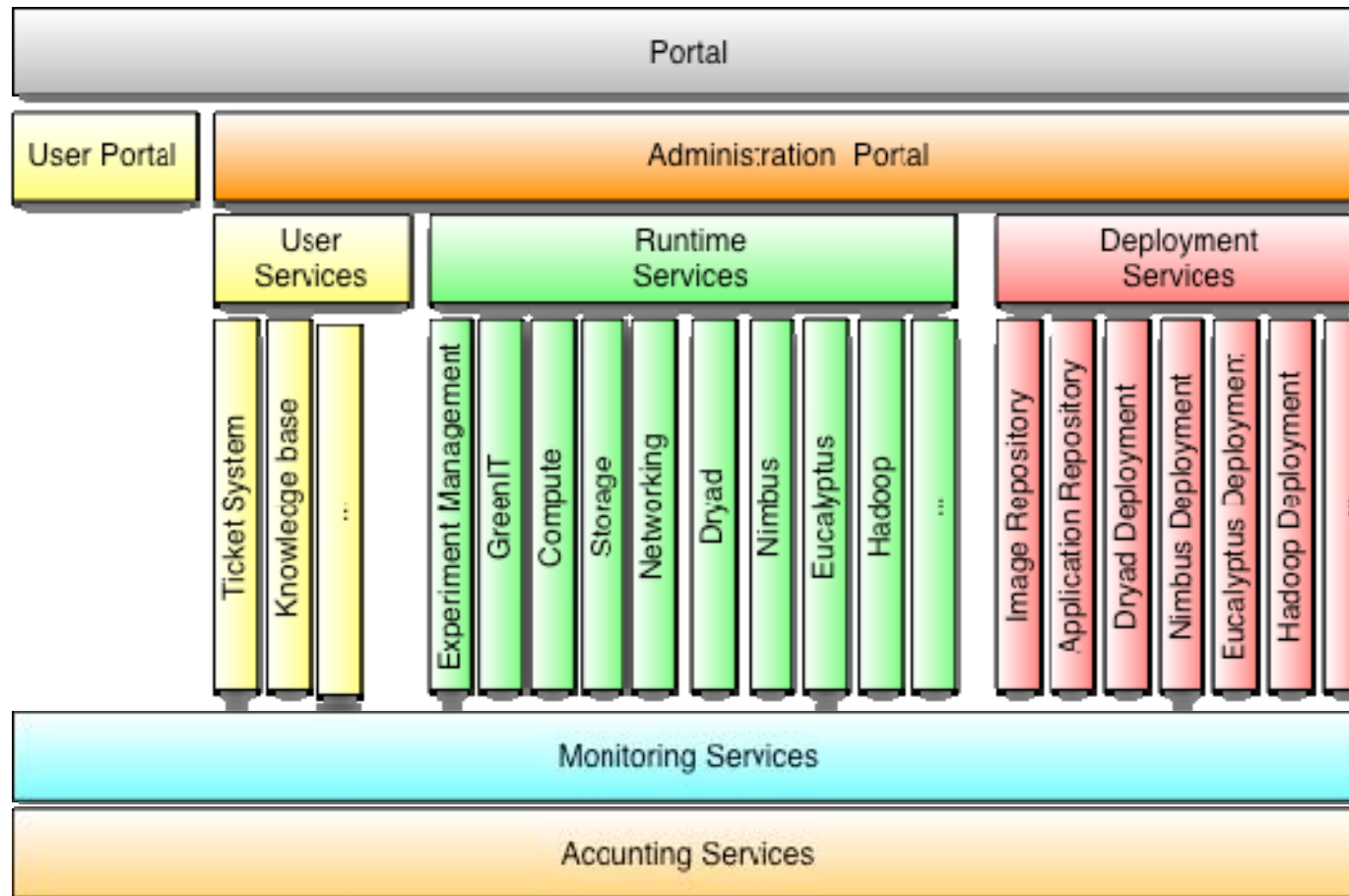
User Portal



FG Information Portal



FG Administration Portal

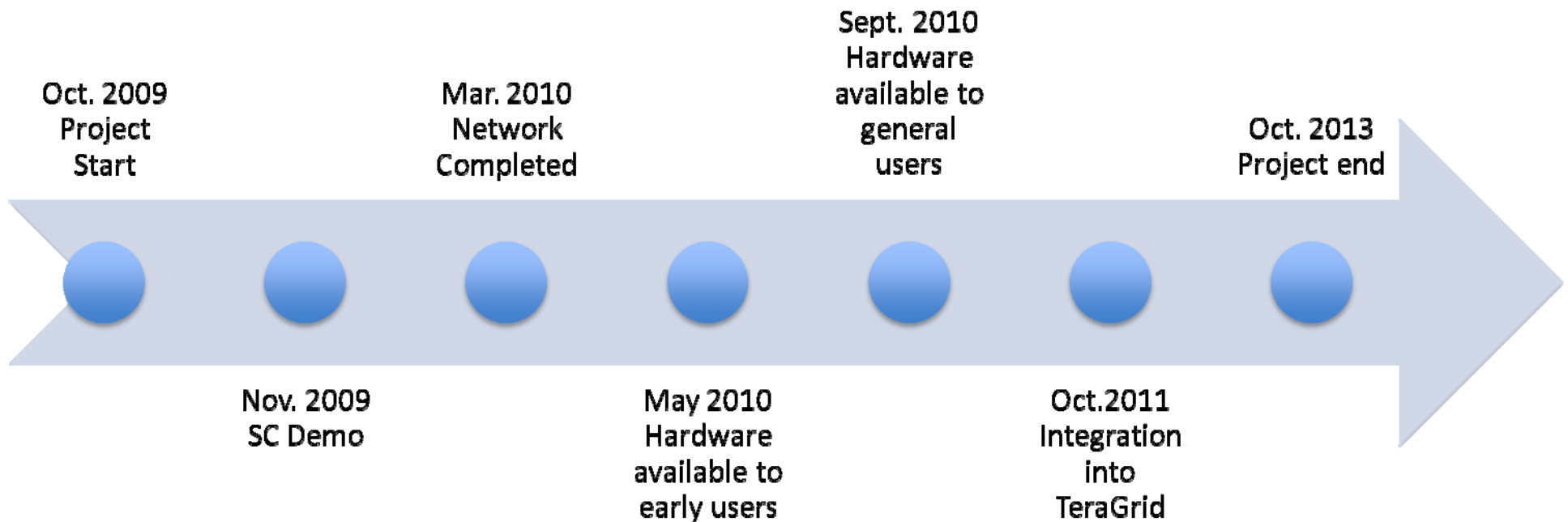


Integration within TeraGrid / TeraGrid XD

- Sure it's part of TeraGrid
- Allocation: separate from TG processes for two years
- It is a very exciting project, it will teak effort
 - TG may change, good that we can wait
- We are looking for early adopters!



Milestones





Questions

- Please contact Gregor via mail
 - laszewski@gmail.com
- We will update our web page soon
 - <http://futuregrid.org>