

Edge Computing and Microscopy: Autonomous and Automated Experiments Leveraging Advances in Computing, Control Systems and Algorithms

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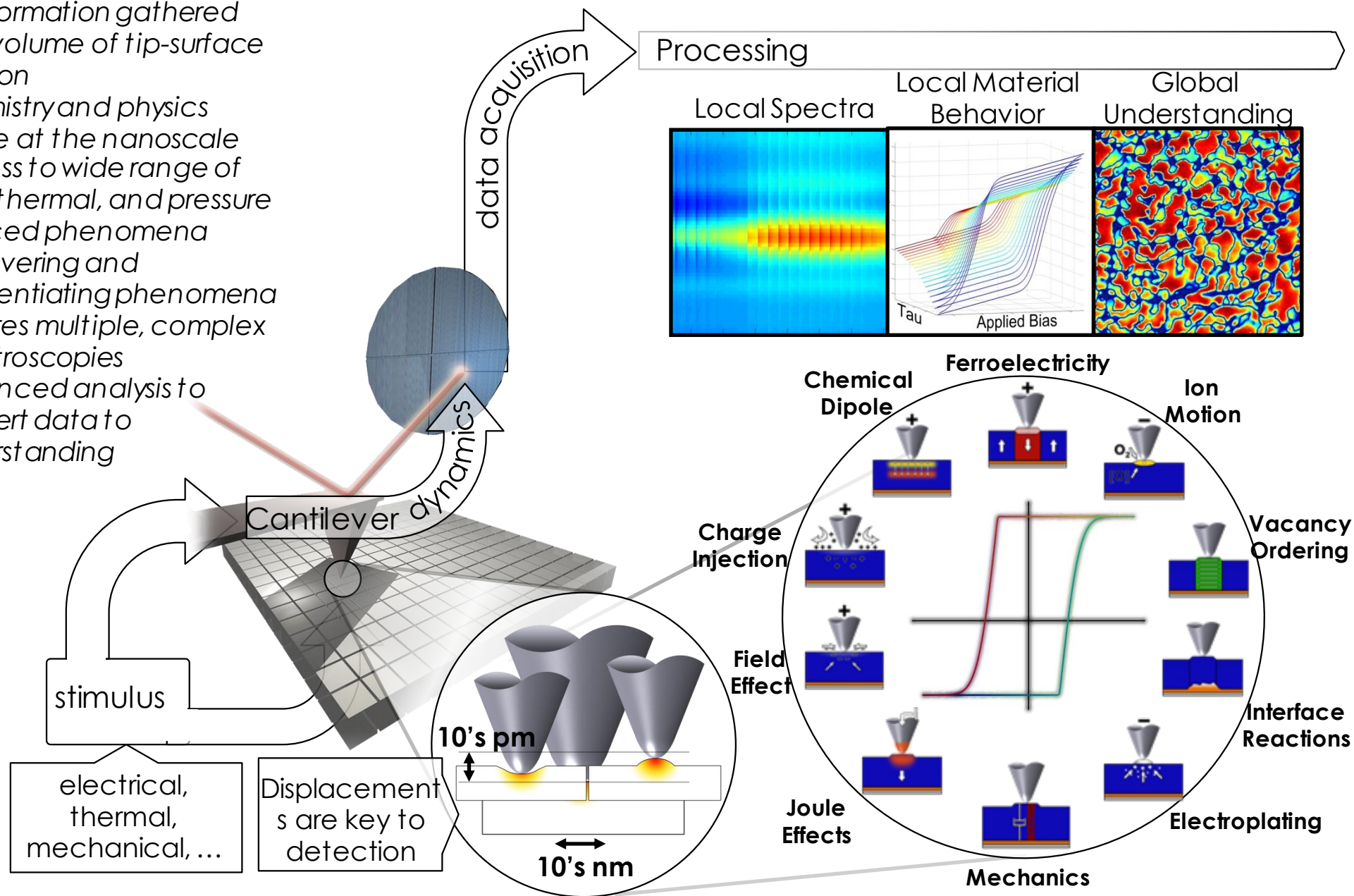
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U.S. DEPARTMENT OF
ENERGY

Information flow in SPM

- All information gathered from volume of tip-surface junction
- Chemistry and physics merge at the nanoscale
- Access to wide range of bias, thermal, and pressure induced phenomena
- Discovering and differentiating phenomena requires multiple, complex spectroscopies
- Advanced analysis to convert data to understanding



Slide by S. Jesse

Automated and Autonomous Experiments in Electron and Scanning Probe Microscopy

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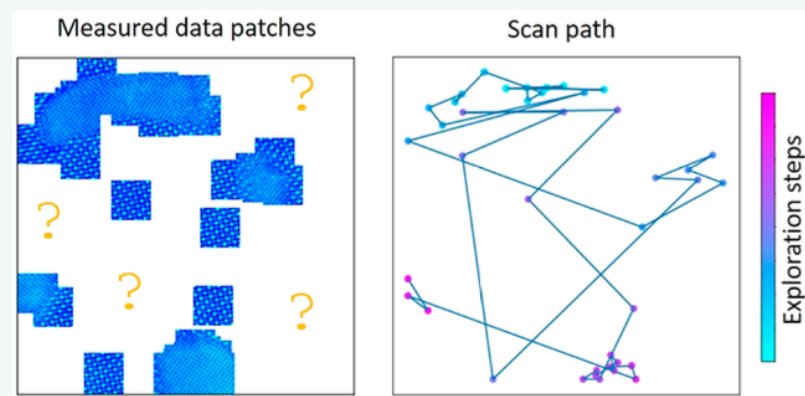


Metrics & More



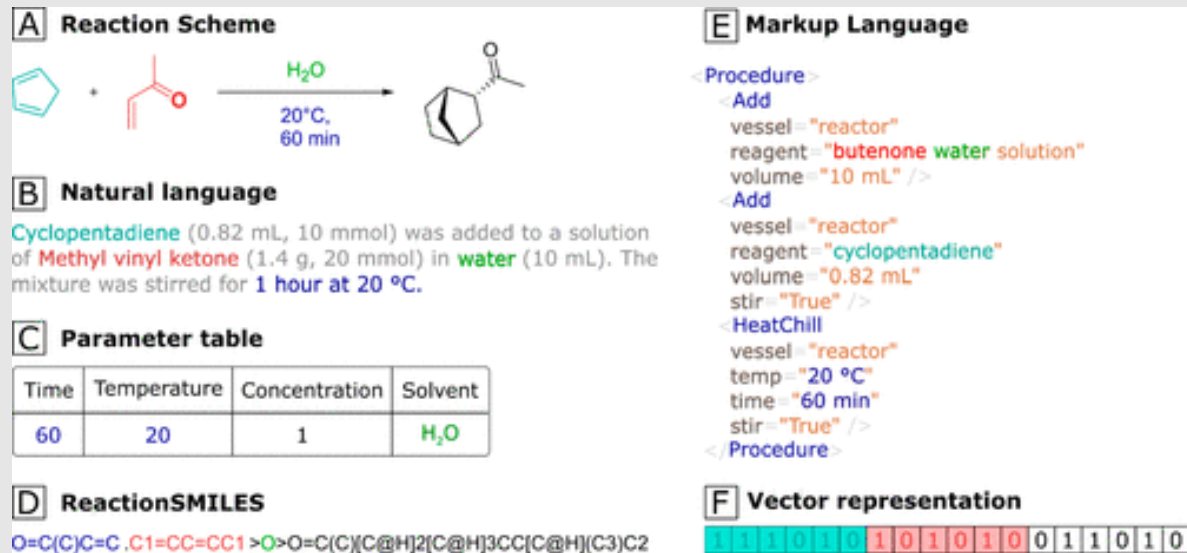
Article Recommendations

ABSTRACT: Machine learning and artificial intelligence (ML/AI) are rapidly becoming an indispensable part of physics research, with domain applications ranging from theory and materials prediction to high-throughput data analysis. In parallel, the recent successes in applying ML/AI methods for autonomous systems from robotics to self-driving cars to organic and inorganic synthesis are generating enthusiasm for the potential of these techniques to enable automated and autonomous experiments (AE) in imaging. Here, we aim to analyze the major pathways toward AE in imaging methods with sequential image formation mechanisms, focusing on scanning probe microscopy



Abstractions make the (automated) world go round

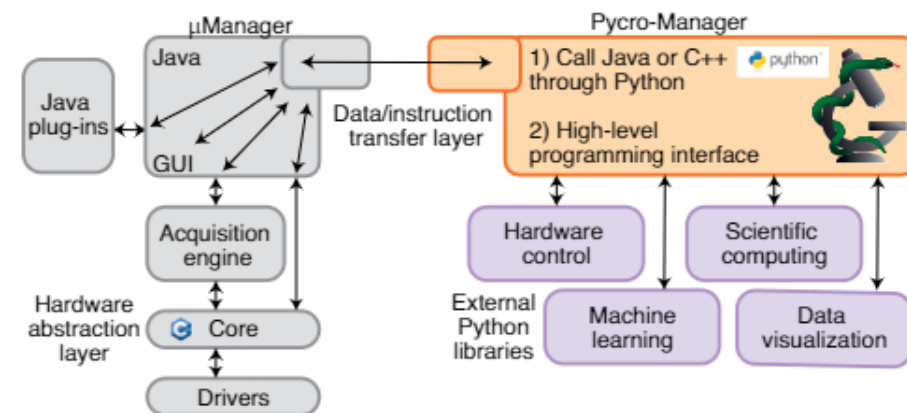
“Chemputation” – Digital chemistry



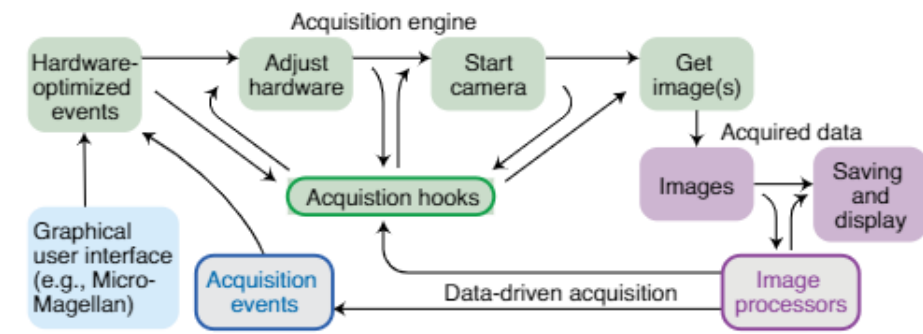
Hammer, Leonov, Bell and Cronin, JACS 1, 1572 (2021)

A complete programming language for chemistry that can run on open hardware

PycroManager

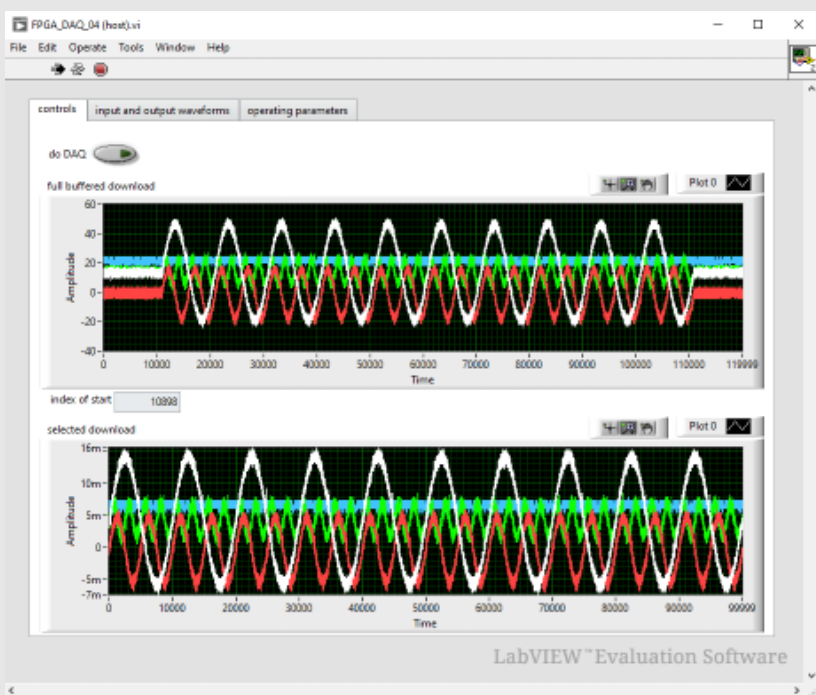


b Pycro-Manager high-level programming interface



Pinkard, et al. Nat. Methods. 18, 226 (2021)

Hardware abstraction - FPGA



Software abstraction - python

```
# Pole half the sample
# Locate the position of the wall
# Randomly select a location on the wall, and randomly select a bias pulse magnitude and pulse width
# Move tip to that location and apply a bias pulse, move the tip back to the start
# Then scan to observe effects

wall_bias_locs = []

for k in range(num_iters):
    if k%reset_freq==0:
        print("on iteration {} of {}, resetting the wall".format(k, num_iters))
        data_output, d, x, y = raster_scan(volt, pix, num_lines, IO_rate, trig, offsetvx, offsetvy, tip_volt=reset_bias,
        apply_half=True, left_bias=False)

        last_x_pos = x[-1]
        last_y_pos = y[-1]
        first_x_pos = x[0]
        first_y_pos = y[0]

        move(last_x_pos, first_x_pos, last_y_pos, first_y_pos, move_speed) #at beginning of scan, move to starting p
        data_output, d, x, y = raster_scan(volt, pix, num_lines, IO_rate, trig, offsetvx, offsetvy, tip_volt=reset_bias,
        apply_half=True, left_bias=True)
        move(last_x_pos, first_x_pos, last_y_pos, first_y_pos, move_speed) #at beginning of scan, move to starting p

    #Do a standard scan, without any bias.
    data_output, d, x, y = raster_scan(volt, pix, num_lines, IO_rate, trig, offsetvx, offsetvy, tip_volt=0.0,
    apply_half=False)
    data_collected.append(data_output)

else:
    #find the mean wall position
    amp_img = data_output[2].reshape(-1, pix*2)[:,:pix]
    phase_img = data_output[2].reshape(-1, pix*2)[:,:pix]
    bias_amp, bias_pw, wall_x_pos, wall_y_pos, xpos_v, ypos_v = get_next_action(amp_img, phase_img, pix=pix)
```

Call low-level functions to control tip position, scanning (e.g., raster, spiral, move etc.), specify voltage waveforms, collect data all in Jupyter notebook

Enables design of complicated automated and autonomous experiments, hardware independent

Instrument 1

Instrument 2

Hardware connection layer



Software layer

```
82 move(last_x_pos, first_x_pos, last_y_pos, first_y_pos, move_speed) #at beginning
83
84 my_results = {'results': data_collected, 'wall_locs': wall_bias_locs}
85 pickle.dump(my_results, open("wall_pulsing_revised_smaller_PTO_40deg.p", "wb"))

on iteration 0 of 501, resetting the wall
on iteration 1 of 501, PFM scan after applying -3.35V 285.55ms pulse at wall position
on iteration 2 of 501, PFM scan after applying -3.93V 199.25ms pulse at wall position
on iteration 3 of 501, PFM scan after applying -4.98V 110.52ms pulse at wall position
on iteration 4 of 501, PFM scan after applying -2.31V 134.52ms pulse at wall position
on iteration 5 of 501, PFM scan after applying -2.58V 330.86ms pulse at wall position
on iteration 6 of 501, PFM scan after applying 0.16V 138.60ms pulse at wall position
on iteration 7 of 501, PFM scan after applying -8.43V 62.23ms pulse at wall position
on iteration 8 of 501, PFM scan after applying -5.31V 260.58ms pulse at wall position
on iteration 9 of 501, PFM scan after applying -9.94V 300.36ms pulse at wall position
on iteration 10 of 501, resetting the wall
```

User

Progress: Real-time automated experiments in SPM

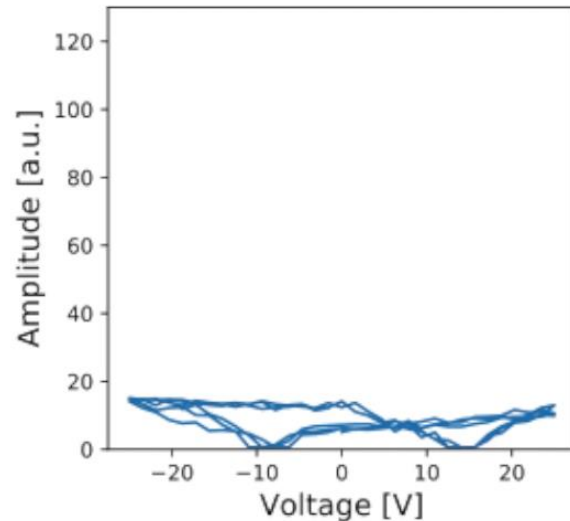
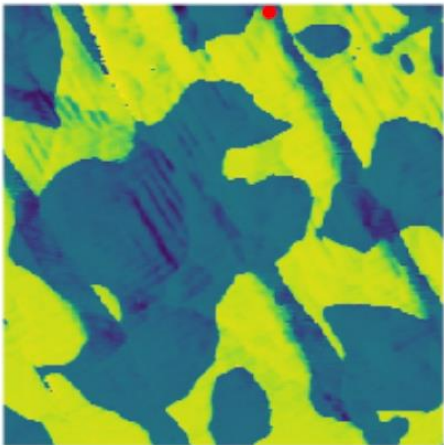
In-line inference

Raw Image

Domain Wall



Image-based feature finding



Streaming functional fitting during scanning on the microscope

Instrument



'Gateway' server



GPU Server



SHO Gen - Jupyter Notebook

2 of 2 matches Beg

SHO Gen Last Checkpoint: 2 minutes ago (autosaved)

View Insert Cell Kernel Widgets Help

Run Code

```
data_recv = s.recv(256)

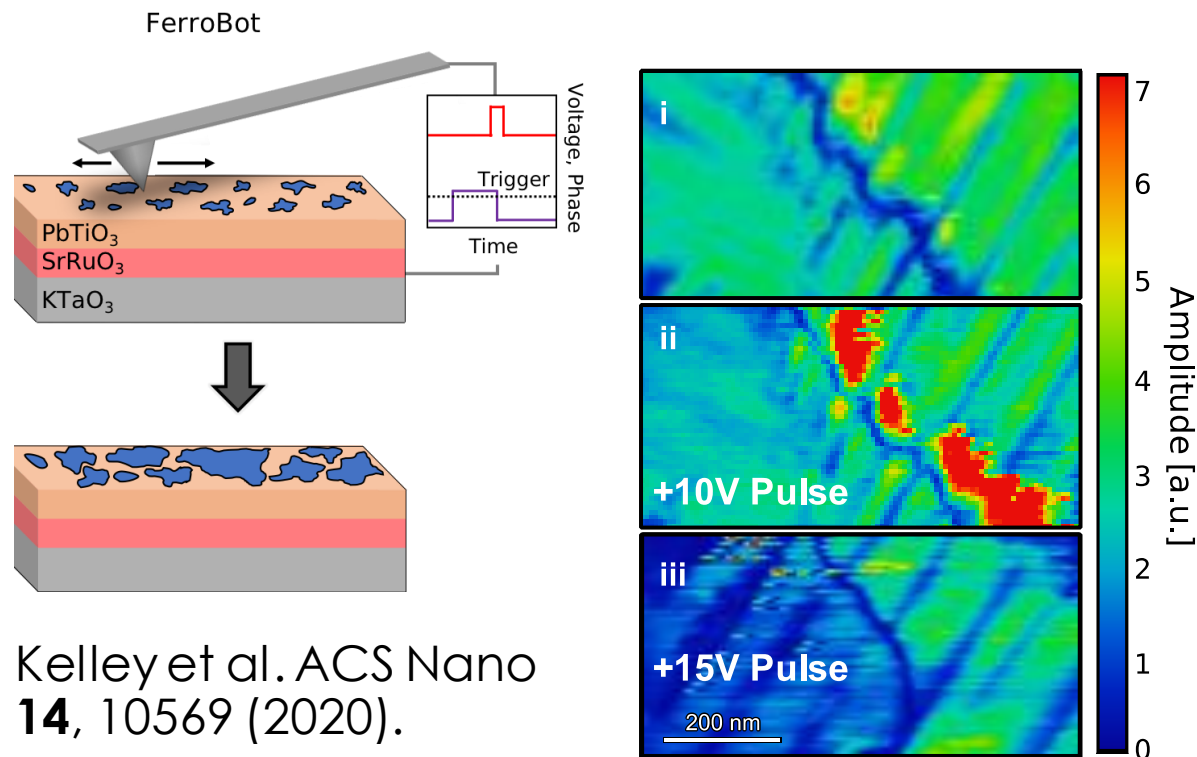
if i>0:
    sho_fit_mat[i-1,:,:] = data_recv
    clear_output(wait=True)
    fig, axes = plt.subplots(nrows=1, ncols=4, figsize=(12,4))
    ax_amp = axes[0].imshow(sho_fit_mat[:, :, 0], vmin = 0, vmax = 0.5)
    ax_wr = axes[1].imshow(sho_fit_mat[:, :, 1], vmin = 0, vmax = 1.0)
    ax_q = axes[2].imshow(sho_fit_mat[:, :, 2], vmin = 0, vmax = 1.0)
    ax_ph = axes[3].imshow(sho_fit_mat[:, :, 3], vmin = 0, vmax = 1.0)
    print('Received SHO parms for line {}'.format(i))

    draw(), pause(1E-3)
```

Received SHO parms for line 57



“Smart” Microscopy Experiments



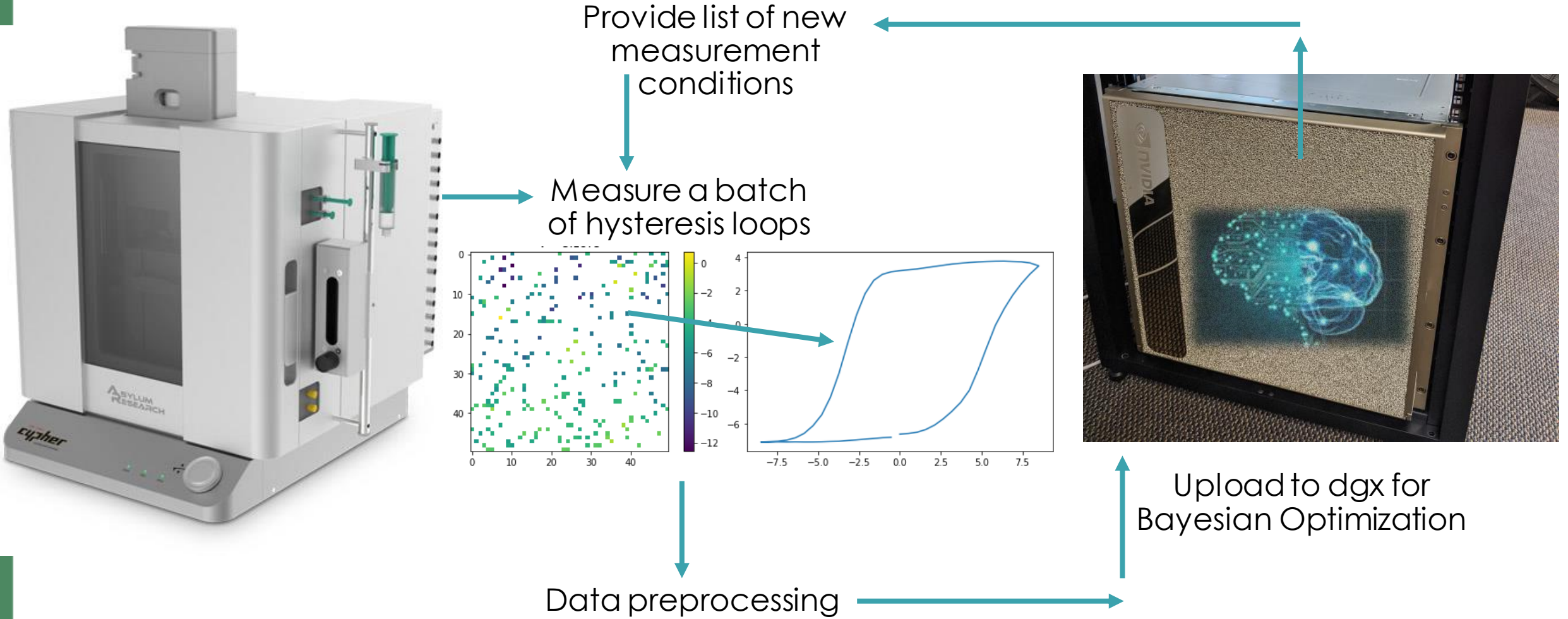
Techniques

- Adaptive sampling
- Structure-triggered events
- Streaming analysis with model comparisons “on the fly”

Yields:

- Enables more efficient and more complex measurements
- Engineering new metastable states
- Better hypothesis testing for physics discovery

Real-time automated SPM



- For long spectroscopies, measuring every pixel across a grid is not feasible. Bayesian optimization enables sampling only those points that will maximize a property of choice, enabling new experiments that would otherwise not be possible


```

root@d83e0a0621c0: /AE x yla@sdgx-server: ~ x Windows PowerShell x + x
Using channel 1
training starts
training finishes
send next point idx and next point: 13397 [191 202]
new data received

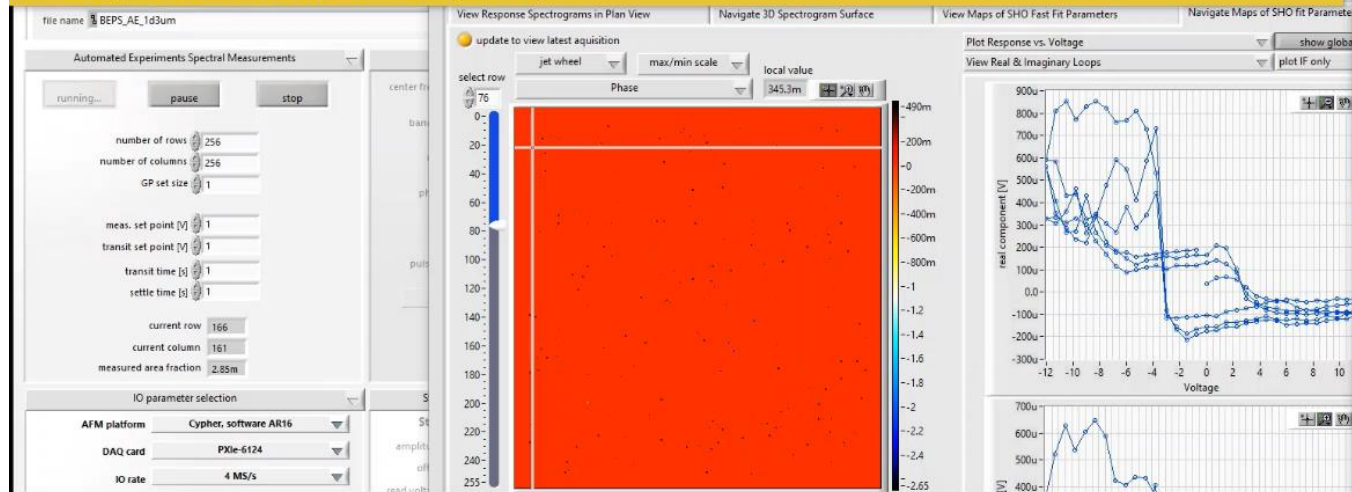
Rewards:
channel 1: counts 37 reward (avg) 0.568
channel 2: counts 23 reward (avg) -0.13
channel 3: counts 22 reward (avg) -0.091
channel 4: counts 23 reward (avg) -0.13
total time in this step: 27.810515642166138

#####--Exploration step 26/200--#####
Using channel 1
training starts
training finishes
send next point idx and next point: 50723 [104 76]
new data received

Rewards:
channel 1: counts 38 reward (avg) 0.579
channel 2: counts 23 reward (avg) -0.13
channel 3: counts 22 reward (avg) -0.091
channel 4: counts 23 reward (avg) -0.13
total time in this step: 31.155067920684814

#####--Exploration step 27/200--#####
Using channel 2
training starts
training finishes
send next point idx and next point: 8898 [161 166]

```

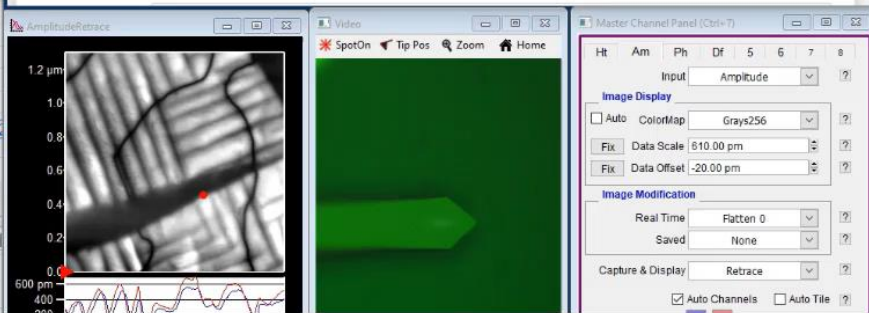


```

Desktop/Yongtao/PTO_DGX/ x ensembledkl_control - Jupyter N x + x
localhost:8888/notebooks/Desktop/Yongtao/PTO_DGX/ensembledkl_control.ipynb
Asylum Research Asylum Support Asylum Forum Asylum Store CADES Gateway
jupyter ensembledkl_control (unsaved changes) Logout
File Edit View Insert Cell Kernel Widgets Help Trusted Python 3 (ipykernel)
Run Code
0.37964419 0.22250361 0.09430258 0.01126451 0.47424365 0.04059401
0.00283926 0.09028857 0.09943439 0.14401162 0.57374739 0.83112309
0.76286022 0.07762122 0.15712405 0.42738201 0.94645701 0.04237785
0.45984606 0.00695146 0.20098208 0.17907475 0.00350927 0.1388772
0.56813351 0.00889883 0.42460984 0.16993114 0.22049039 0.54476878
0.16502392 0.59338362 0.23389051 0.38796662 0.38528072 0.14889388
0.59553218 0.63365998 0.03145237 0.20104512 0.18783626 0.63186222
0.25532897 0.01773822 0.0415196 0.47719055 0.07378896 0.01079252
0.08988518 0.40889152 0.64642275 0.04966939 0.20664814 0.03103124
0.57772826 0.48393934 0.0151609 0.00327395 0.7168221 0.00585883
0.66714498 0.13343161 0.0474365 0.06671236 0.70277997 0.01635374
0.00889438 0.804201 0.06254023 0.67869679 0.01380923 0.12327883
0.59952096 0.49286824 0.64990843 0.20136401 0.06793601 0.22224563
0.10182442 0.06336973 0.32129096 0.71645918 0.07285707 0.14496909
0.52270663 0.00485219 0.01879533 0.00294088 0.36995164 0.59461561
0. 0.18649218 0.00473465 0.62753335 0.45032077 0.2530051
0.10272701 0.05852992 0.24070122 0.01151899 0.05797015 0.06092061
0.12344335 0.75507833 0.09716855 0.64386291 0.0148364 0.55460357
0.37179332 0.78634043 0.15908792 0.18301838 0.04637307 0.84543375
0.00670266 0.67030528 0.07696244 0.05186789 0.05416548 0.58353605
0.50419737 0.11847592 0.11166726 0.11764638 0.04241899 0.16650697
0.07441622 0.09790933 0.04508854 0.80219772 0.04460034 0.435546
0.38386068 0.05571796 0.01184468 0.0424554 0.23185985 0.24666497
0.2919818 0.02549241 0.57926039 0.80193889 0.16956717 0.07659509
0.03690842 0.03093944 1. 0.58478088 0.08151939 0.45842916
0.59269589 0.00717443 0.06801086 0.06455179 0.08339584 0.10857291
0.0537608 0.04916218 0.045514 0.41319159 0.76745094 0.36118681
0.87138119 0.90536946 0.00200154 0.05376027 0.23197932 0.60147377
0.44870718]
time in this step: 31.142277479171753
measurement 46
predicted point ready [161 166]
flip: [166 161]

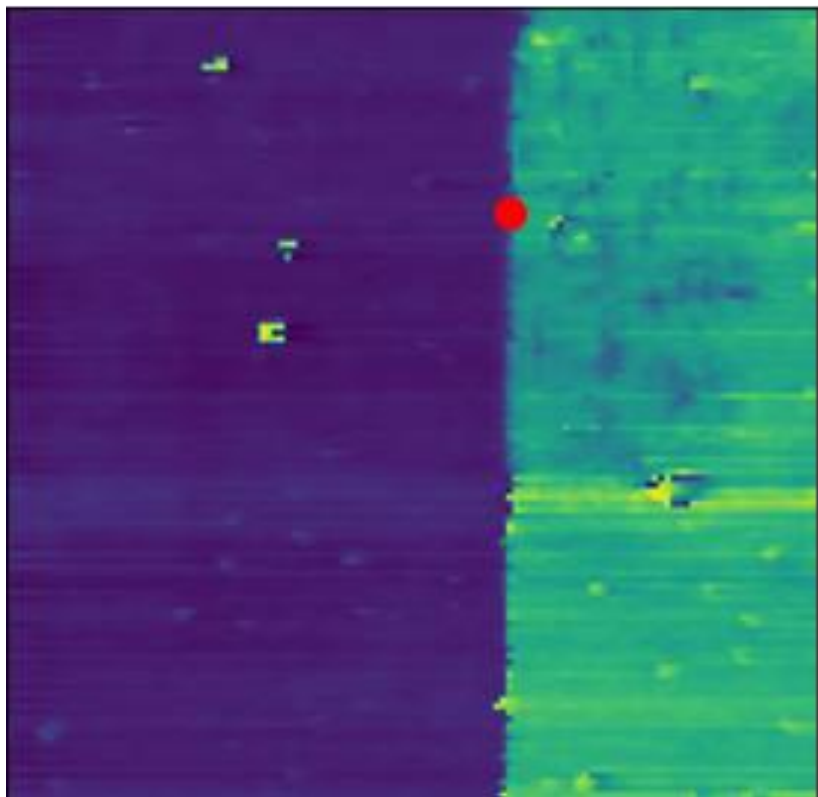
In [ ]:

```



Autonomous workflows

Materials design problem in microscopy: how we can modify materials intelligently



Domain
knowledge,
Simulations



Workflow

Write
automation
script

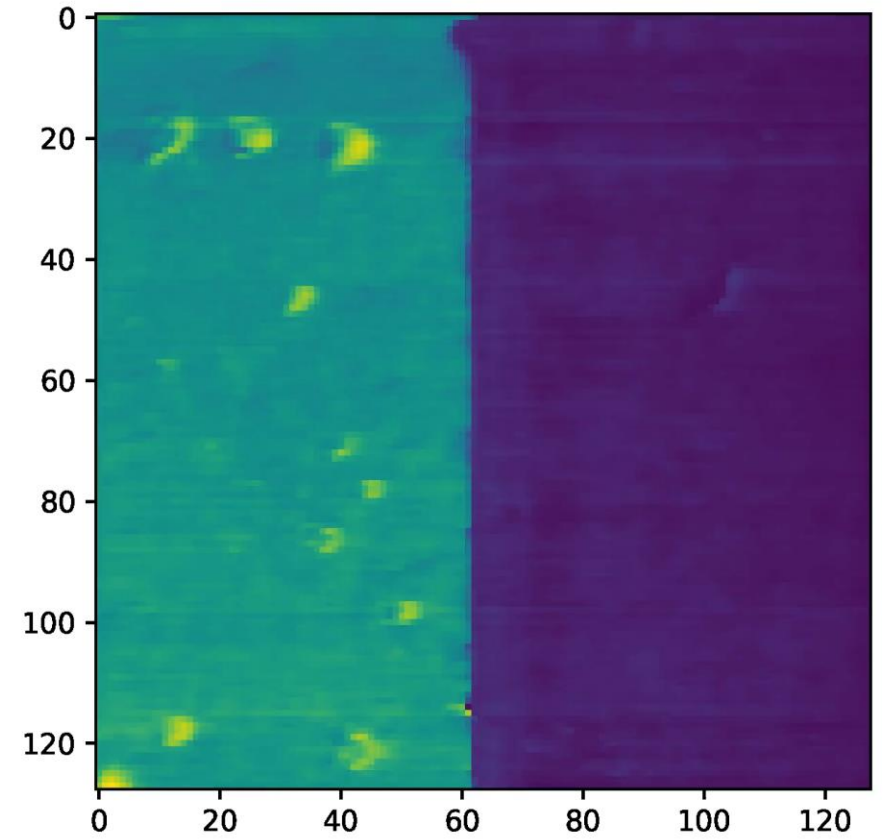
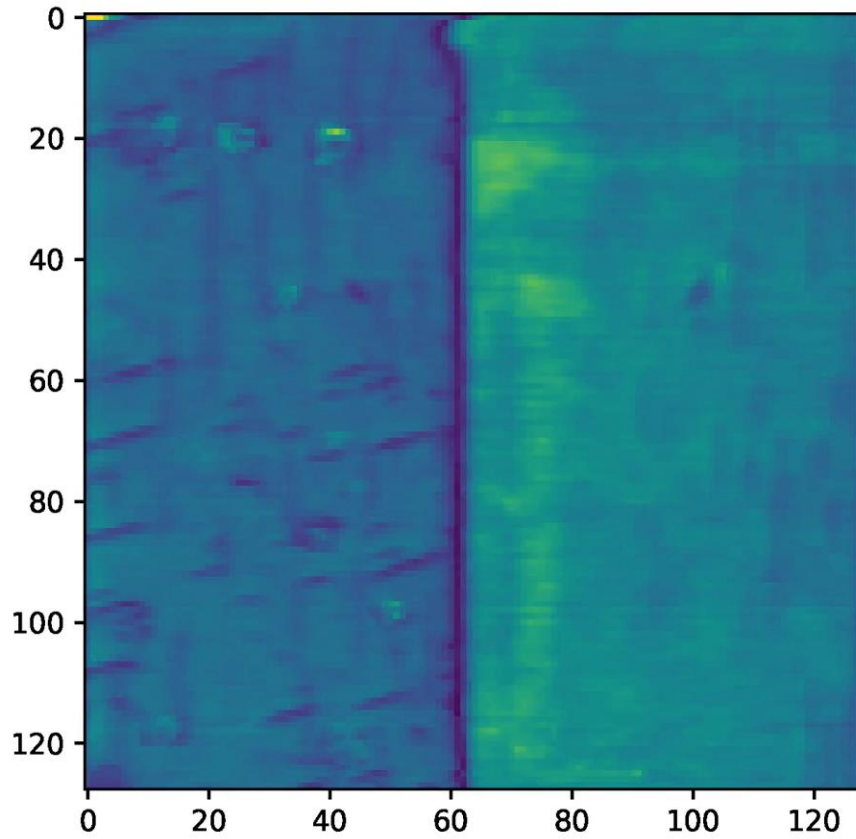
Collect data on
state transitions
with policy

From data, train
a surrogate
model

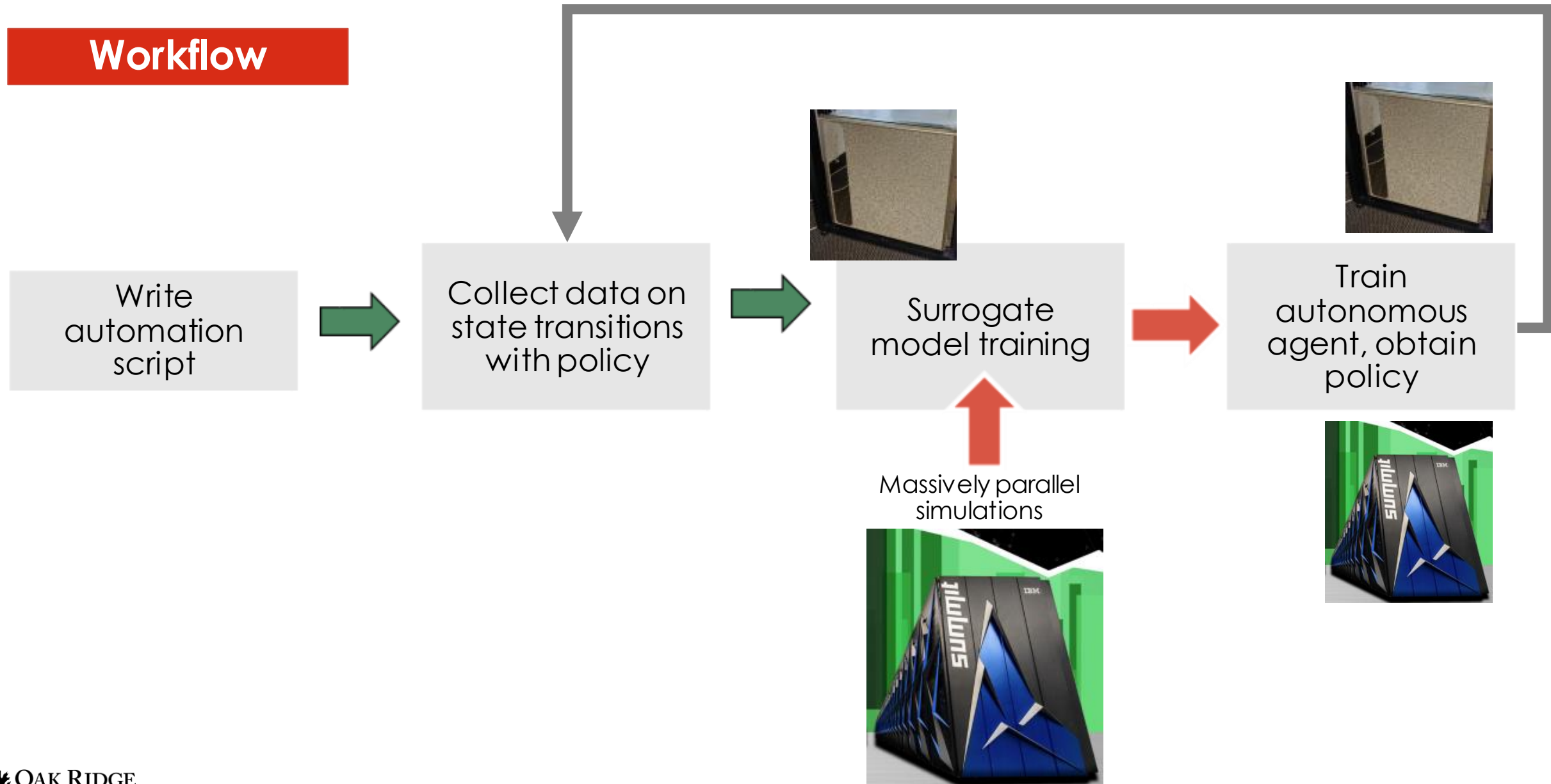
Train
autonomous
agent, obtain
policy

Update Policy

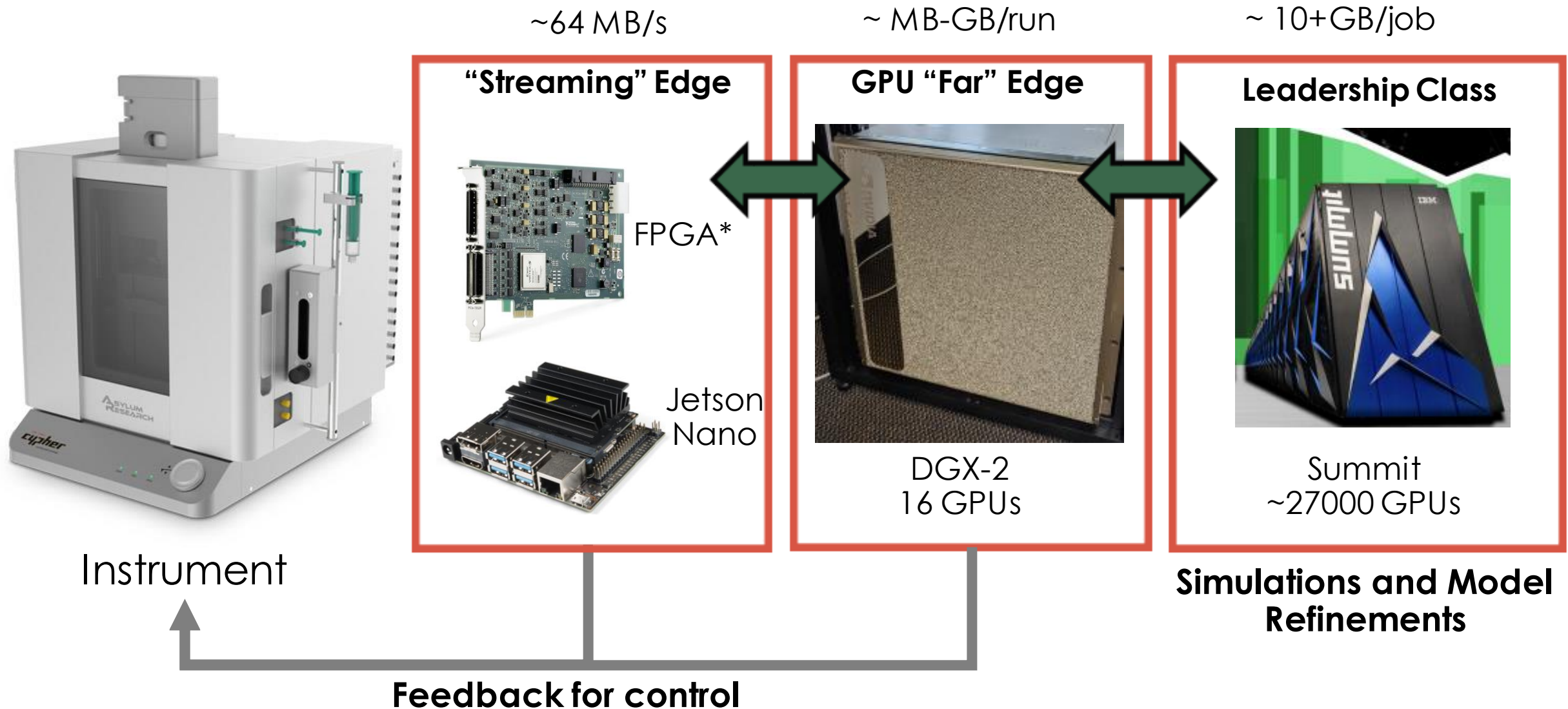
Random Policy-> data collection



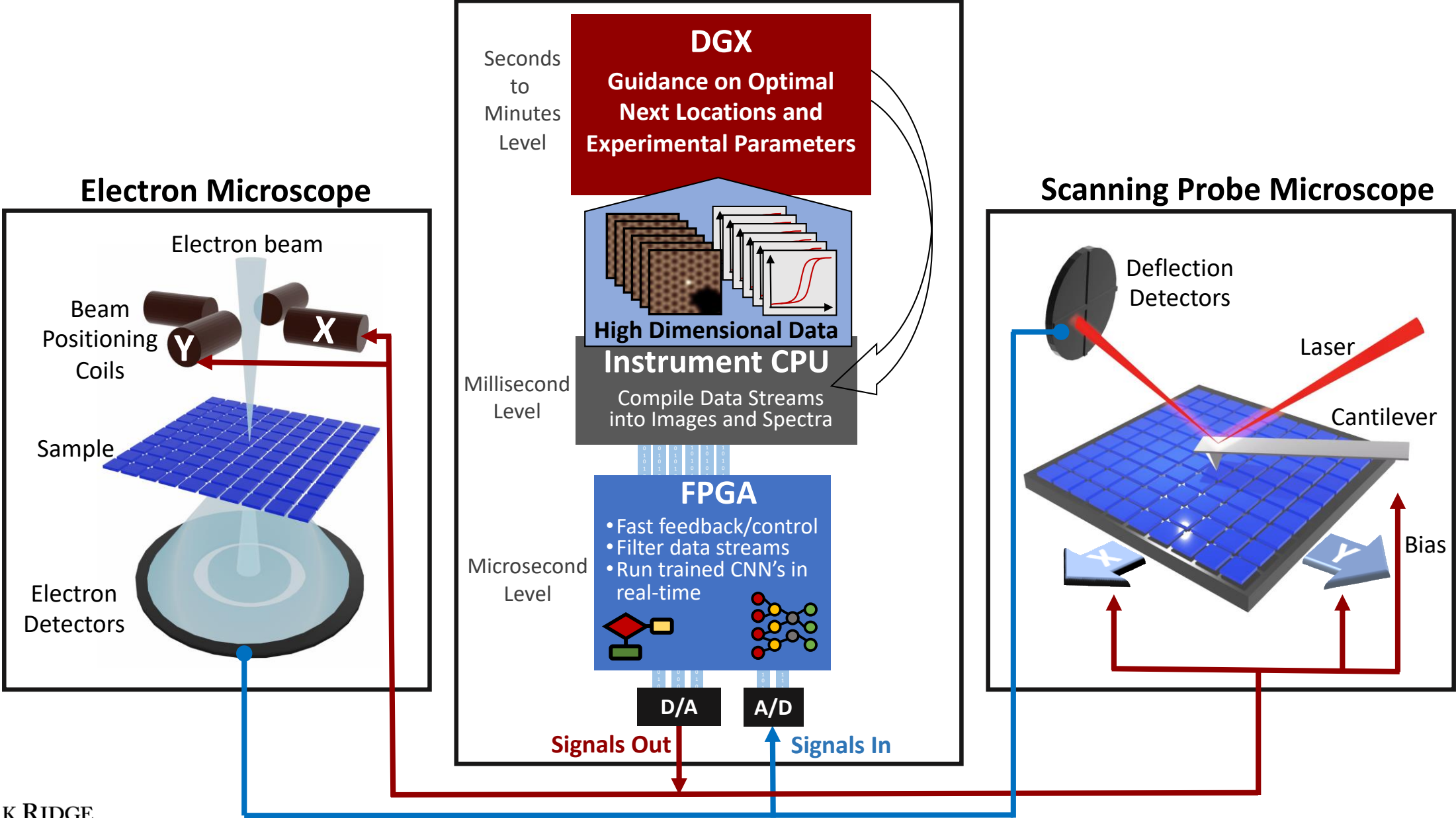
Workflow elaboration (future idea – not current)



Computational Needs: Streaming, Near Edge and HPC



Edge Computing at the Instrument Level



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